

Review:

Undirected graph  $G = (V, E)$    
nodes  $V$    
undirected edges  $E$

Degree matrix of  $G$ :  $\Delta(G) = \begin{pmatrix} d(v_1) & & 0 \\ & d(v_2) & \\ 0 & & \dots & d(v_n) \end{pmatrix}$    
 (diagonal)

Adjacency matrix of  $G$ :  $A(G) = [a_{ij}]$  where  $a_{ij} = \begin{cases} 1 & \text{if } v_i v_j \in E \\ 0 & \text{otherwise} \end{cases}$    
 (symmetric)   
unordered

Incidence matrix  $G$  (undirected):

Pick an arbitrary direction for each edge in  $G$  to get a directed graph  $G^\circ$ , then:

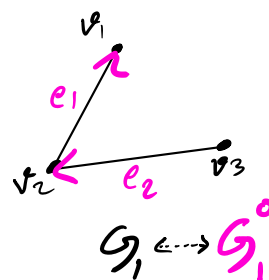
(nodes x edges)  $D(G^\circ) = [d_{ij}]$  where  $d_{ij} = \begin{cases} -1 & \text{if } v_i \text{ is the tail of } e_j \\ 1 & \text{if } v_i \text{ is the head of } e_j \\ 0 & \text{o.w.} \end{cases}$

graph Laplacian of  $G$ :  $L(G) \cong \Delta(G) - A(G) \stackrel{\text{(why?)}}{=} D(G^\circ) D(G^\circ)^T$

weighted graph Laplacian:  $L_w(G) = D(G^\circ) W D(G^\circ)^T$  where  $W = \text{diag}(w(e_1), \dots, w(e_m))$

Example:

$\Delta(G_1) = \begin{pmatrix} \downarrow v_1 & \downarrow v_2 & \downarrow v_3 \\ 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}, A(G_1) = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$



$D(G_1^\circ) = \begin{bmatrix} \downarrow e_1 & \downarrow e_2 \\ 1 & 0 \\ -1 & 1 \\ 0 & -1 \end{bmatrix}, L(G_1) = \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} = D(G_1^\circ) D(G_1^\circ)^T \leftarrow \text{(sym.)}$

If  $w(e_1) = 5, w(e_2) = 7 \Rightarrow L_w(G_1) = \begin{bmatrix} 1 & 0 \\ -1 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 5 & -5 & 0 \\ -5 & 12 & -7 \\ 0 & -7 & 7 \end{bmatrix}$

Can you guess how to define "weighted adjacency/degree" matrices for  $G$  (undirected) ?!

Directed graph  $\mathcal{D} = (V, E)$  directed edges.  
 $\uparrow$  nodes.

Incidence matrix of  $\mathcal{D}$ :

since  $\mathcal{D}$  already has orientation  $\Rightarrow D(\mathcal{D}) = [d_{ij}]$

Adjacency matrix of  $\mathcal{D}$  with edge weights  $w_{ij}$  on edge  $(\vec{v}_j, v_i)$ :

(not symmetric)  $A(\mathcal{D}) \cong [\vec{a}_{ij}]$  where  $\vec{a}_{ij} = \begin{cases} w_{ij} & \text{if } (\vec{v}_j, v_i) \in E \\ 0 & \text{o.w.} \end{cases}$  ordered

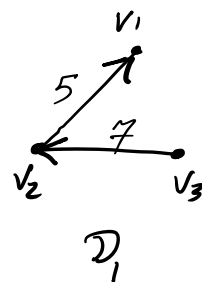
Weighted in-degree matrix of  $\mathcal{D}$ :

$\Delta(\mathcal{D}) = \text{diag}(d_{in}(v_1), \dots, d_{in}(v_n))$  with  $d_{in}(v_i) = \sum_{\{j \mid (\vec{v}_j, v_i) \in E(\mathcal{D})\}} w_{ij}$

weighted in-degree Laplacian of  $\mathcal{D}$ : (not symmetric)  $L(\mathcal{D}) \cong \Delta(\mathcal{D}) - A(\mathcal{D})$

Example:

$$\Delta(\mathcal{D}_1) = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad A(\mathcal{D}_1) = \begin{bmatrix} 0 & 5 & 0 \\ 0 & 0 & 7 \\ 0 & 0 & 0 \end{bmatrix},$$



incidence matrix

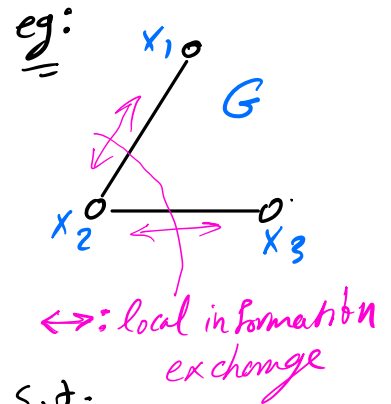
$$D(\mathcal{D}_1) = \begin{bmatrix} 1 & 0 \\ -1 & 1 \\ 0 & -1 \end{bmatrix}, \quad L(\mathcal{D}_1) = \begin{bmatrix} 5 & -5 & 0 \\ 0 & 7 & -7 \\ 0 & 0 & 0 \end{bmatrix} \leftarrow \text{(not sym.)}$$

# Agreement Protocol (Consensus)

Let us assign a scalar state " $x_i$ " to each node  $i$  in  $G$  (undirected).

$N_i$ : set of nodes adjacent to " $i$ ".

$X := [x_1, \dots, x_n]^T \in \mathbb{R}^n$  concatenation of states



**Goal:** design an update rule for each  $x_i$  s.t.

- all  $x_i$  converge to an "agreement".
- it only uses information "locally"

First-order agreement protocols:

Suppose each node implements the following first-order dynamics

$$\dot{x}_i(t) = \sum_{j \in N_i} (x_j(t) - x_i(t)) \quad \text{for } i = 1, \dots, n.$$

eg.

$$\begin{cases} \dot{x}_1 = x_2 - x_1 \\ \dot{x}_2 = x_1 - x_2 + x_3 - x_2 \\ \dot{x}_3 = x_2 - x_3 \end{cases} \Rightarrow \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} X + \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} X$$

$D(G)$                        $A(G)$

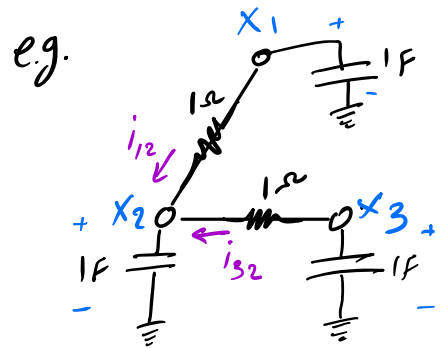
So, this can be compactly represented as

$$\dot{X}(t) = - [ \overset{\substack{\text{degree matrix} \\ \uparrow}}{D(G)} - \overset{\substack{\text{adjac.} \\ \text{matrix} \\ \uparrow}}{A(G)} ] X(t) = - \overset{\substack{\text{Laplacian matrix} \\ \uparrow}}{L(G)} X(t)$$

## Circuit interpretation :

- replace the edges with unit resistors
- connect a linear unit capacitor from each node to "ground".
- let each  $x_i(t)$  denote the initial capacitor charge at node  $i$ .

$$\begin{array}{l} \begin{array}{c} + \quad V \quad - \\ \rightarrow | \quad | \quad | \\ i \quad C \end{array} \quad i = C \frac{dV}{dt} \\ \begin{array}{c} + \quad V \quad - \\ \rightarrow | \quad | \quad | \\ i \quad R \end{array} \quad V = iR \end{array}$$



## Kirchhoff's current law at node 2:

$$\begin{aligned} 1 \cdot \frac{dx_2}{dt} &= i_{12} + i_{32} \\ &= (x_1 - x_2) \cdot 1 + (x_3 - x_2) \cdot 1 \end{aligned}$$

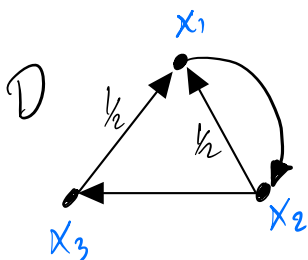
So, Kirchhoff's current-voltage law at node "i" implies:

$$\dot{x}_i(t) = \sum_{j \in N_i} (x_j(t) - x_i(t))$$

but this is the same as our agreement protocol.

Q: Now, what if the information network is directed (D)?!

E.g.



Agreement protocol:

$$\begin{cases} \dot{x}_1 = \frac{1}{2}(x_3 - x_1) + \frac{1}{2}(x_2 - x_1) \\ \dot{x}_2 = x_1 - x_2 \\ \dot{x}_3 = x_2 - x_3 \end{cases}$$

$$\Rightarrow \begin{bmatrix} \dot{x}_1 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = - \underbrace{\begin{bmatrix} +1 & 0 & 0 \\ 0 & +1 & 0 \\ 0 & 0 & +1 \end{bmatrix}}_{\Delta(D)} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \underbrace{\begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{2} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}}_{A(D)} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

(in-degree matrix of  $D$ )  $\uparrow$   $\Delta(D)$       in-degree adjacency matrix of  $D$   $\uparrow$   $A(D)$

$\Rightarrow$  Agreement protocol for directed graph:

$$\dot{X} = -(\Delta(D) - A(D))X = -L(D)X$$

$\uparrow$   
in-degree Laplacian matrix of  $D$ .

Q: Are these procedures actually working towards an agreement?

Define: the "Agreement set"  $\mathcal{A} \subseteq \mathbb{R}^n$  is the subspace  $\text{span}\{1\}$

i.e.

$$\mathcal{A} = \{x \in \mathbb{R}^n \mid x_i = x_j, \forall i, j\}$$

Note that both agreement protocols are stationary on the agreement set  $\mathcal{A}$ . why?

recall that  $L(G)1 = 0$  and  $L(D)1 = 0$ .